

So far, we have discussed convexity in the linear sense (i.e. the convex combinations of μ_0, μ_1 are the mixtures of the form $[1-t]\mu_0 + t\mu_1$ for $t \in [0,1]$). This does not respect the geometric structure of Wasserstein space and motivates the following.

Defn: Let X be a geodesic metric space and $F: X \rightarrow \mathbb{R} \cup \{\pm\infty\}$ a functional on X . We say F is geodesically convex if $\forall x_0, x_1 \in X$ there exists a constant speed geodesic $w: [0,1] \rightarrow X$ s.t. (i) $w(0) = x_0, w(1) = x_1$
(ii) $t \mapsto F(w(t))$ is convex.

Remark: if geodesics in X are line segments (e.g., in \mathbb{R}^d or any normed vector space), this reduces to the usual notion of convex functions!

In our setting of W_p equipped with the Wasserstein- p metric, we know that geodesics are given by certain pushforwards related to the optimal coupling (or map in certain cases), namely if $\mu_0, \mu_1 \in W_p$ have OT plan π , then ~~the~~ a constant speed geodesic is given by

$$\mu_t = \int_{P_t} \pi, \quad \gamma_t(x,y) = (1-t)x + ty$$

Let's look at conditions that guarantee certain functionals we've become familiar with are geodesically convex, which we call displacement convex in Wasserstein space, after McCann.

Proposition (Displacement Convexity of Potential Energies): Suppose $V: \mathbb{R}^d \rightarrow \mathbb{R}$ and let $\mathcal{V}: \mathcal{P}(\mathbb{R}^d) \rightarrow \mathbb{R}$ be $\mathcal{V}(\mu) := \int V d\mu$. Then \mathcal{V} is displacement convex $\Leftrightarrow V$ is

Convex.

Proof: \Rightarrow Consider geodesics of the form $\mu_t = \int_{[1-t]x+ty}$. Then notice $V(\mu_t) = V([1-t]x+ty)$, so geodesic convexity of V gives convexity of V .
 \Leftarrow : Suppose V is convex and let μ_t be a constant speed geodesic connecting μ_0 and μ_1 . Then $V(\mu_t) = \int_{\mathbb{R}^d} V(z) d\mu_t(z)$

$$\begin{aligned}
 &= \int_{\mathbb{R}^d} V(\pi_t^{-1}(z)) d\pi_t(z) \\
 &= \int_{\mathbb{R}^d \times \mathbb{R}^d} V([1-t]x+ty) d\pi(x,y) \\
 &\leq \int_{\mathbb{R}^d \times \mathbb{R}^d} ([1-t]V(x) + tV(y)) d\pi(x,y) \\
 &= \int_{\mathbb{R}^d \times \mathbb{R}^d} [1-t]V(x) d\pi(x,y) + \int_{\mathbb{R}^d \times \mathbb{R}^d} tV(y) d\pi(x,y) \\
 &= [1-t] \int_{\mathbb{R}^d} V(x) d\mu_0(x) + t \int_{\mathbb{R}^d} V(y) d\mu_1(y) \\
 &= [1-t]V(\mu_0) + tV(\mu_1) \quad \square
 \end{aligned}$$

Proposition (Displacement Convexity of Interaction Energies): Suppose $W: \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ and let $W: \mathcal{P}(\mathbb{R}^d) \rightarrow \mathbb{R}$ be given by $W(\mu) := \int_{\mathbb{R}^d \times \mathbb{R}^d} W(x,y) d\mu(x) d\mu(y)$. Then

W is displacement convex if W is convex. (3)

Proof: Let $\{\mu_t\}_{t \in [0,1]}$ be a constant speed geodesic between μ_0 and μ_1 . Then

$$W(\mu_1) = \int_{\mathbb{R}^d \times \mathbb{R}^d} W(x, y) d\mu_1(x) d\mu_1(y)$$

$$= \int_{\mathbb{R}^d \times \mathbb{R}^d} W(x, y) d[\tau_t]_{\#} \pi(x) d[\tau_t]_{\#} \nu(y)$$

$$= \int_{\mathbb{R}^d \times \mathbb{R}^d \times \mathbb{R}^d \times \mathbb{R}^d} W([1-t]x + ty, [1-t]\tilde{x} + t\tilde{y}) d\hat{\pi}(x, y) d\hat{\nu}(\tilde{x}, \tilde{y})$$

$$= \int_{\mathbb{R}^d \times \mathbb{R}^d \times \mathbb{R}^d \times \mathbb{R}^d} W([1-t] \begin{pmatrix} x \\ \tilde{x} \end{pmatrix} + t \begin{pmatrix} y \\ \tilde{y} \end{pmatrix}) d\hat{\pi}(x, y) d\hat{\nu}(\tilde{x}, \tilde{y})$$

$$\leq \int_{\mathbb{R}^d \times \mathbb{R}^d \times \mathbb{R}^d \times \mathbb{R}^d} \left([1-t] W(x, \tilde{x}) + t W(y, \tilde{y}) \right) d\hat{\pi}(x, y) d\hat{\nu}(\tilde{x}, \tilde{y})$$

$$= (1-t) \int_{\mathbb{R}^d \times \mathbb{R}^d} W(x, \tilde{x}) d\mu_0(x) d\mu_0(\tilde{x}) + t \int_{\mathbb{R}^d \times \mathbb{R}^d} W(y, \tilde{y}) d\mu_1(y) d\mu_1(\tilde{y})$$

$$= (1-t) W(\mu_0) + t W(\mu_1). \blacksquare$$

Remark: In fact, W convex $\not\Rightarrow W$ is convex; see Prop 7.25 in Santambrogio.

Perhaps counter-intuitively, $\mu \mapsto W_2^2(\mu, \nu)$ is not ~~convex~~ displacement convex: (4)

ex: Let $\nu = \frac{1}{2} \delta_{(1,1)} + \frac{1}{2} \delta_{(-1,0)}$

$$\mu_t = \frac{1}{2} \delta_{(t,a)} + \frac{1}{2} \delta_{(-t,-a)}$$

If $a > 1$, the curve μ_t is \mathbb{R}^2 geodesic between $\frac{1}{2} \delta_{(-1,a)} + \frac{1}{2} \delta_{(1,-a)}$ and $\frac{1}{2} \delta_{(1,a)} + \frac{1}{2} \delta_{(-1,-a)}$ (exercise). But, $W_2^2(\mu_t, \nu) = a^2 + \min\{(1-t)^2, (1+t)^2\}$.

(exercise), which is not convex in t .

This motivates ~~the~~ a new notion of geodesic, such that $\nu \mapsto W_2^2(\mu, \nu)$ is in fact "convex".

Def: Fix $\rho \in \mathcal{P}(\mathbb{R}^d)$. Let $\mu_0, \mu_1 \in \mathcal{P}(\mathbb{R}^d)$. We call the following curve the generalized geodesic between μ_0 and μ_1 with base ρ :

$$\mu_t := \left[(1-t) T_{\rho \rightarrow \mu_0} + t T_{\rho \rightarrow \mu_1} \right] \# \rho$$

where $T_{\rho \rightarrow \mu_0}, T_{\rho \rightarrow \mu_1}$ are the respective OT maps from ρ to μ_i .

So, we are fixing a base measure, taking convex combinations in the linear space $L^2(\mathbb{R}^d, \rho)$, then pushing forward. In fact, this idea is useful in a lot of situations and sometimes goes under the name "linearized OT".

Note that for any ρ and with $\{t\}_{t \in [0,1]}$ as above, we have convexity along the curve:

$$W_2^2(\mu + \frac{\lambda}{t}, \rho) = \min_{T \# \rho = \mu + \frac{\lambda}{t}} \int_{\mathbb{R}^d} \|T(x) - x\|^2 d\rho(x) \quad (T_i := T_{\rho \rightarrow \mu_i})$$

$$\begin{aligned} T &= (1-t)T_0 + tT_1 \\ &\leq \int_{\mathbb{R}^d} \|[1-t]T_0(x) + tT_1(x) - x\|^2 d\rho(x) \\ &\leq (1-t) \int_{\mathbb{R}^d} \|T_0(x) - x\|^2 d\rho(x) + t \int_{\mathbb{R}^d} \|T_1(x) - x\|^2 d\rho(x) \\ &= (1-t)W_2^2(\mu_0, \rho) + tW_2^2(\mu_1, \rho), \text{ as needed.} \end{aligned}$$

The key point is the T above is a transport map, but in general not the OT map.