

Lecture #5

- The central idea of statistics is to infer from data.
- That is, let \bar{X} be some unknown r.v. If we observe $X_1, X_2, \dots, X_n \stackrel{iid}{\sim} \bar{X}$, what can we say about \bar{X} itself?
- Possible questions about \bar{X} :
 - What is the density of \bar{X} ? This is often very hard
 - Does \bar{X} look like it comes from a certain family of distributions?
 - What is $E(\bar{X})$? $Var(\bar{X})$? More generally,

$$\int_{\mathbb{R}} g(x) \cdot f_{\bar{X}}(x) dx \quad \text{for some } g(x).$$

- Two broad directions: parametric v. nonparametric
 - ↓
 - ~ makes strong assumptions
 - ~ easy to work with
 - ↓
 - ~ few assumptions → very flexible
 - ~ more difficult computationally

Defn: A collection of functions \mathcal{F} is a parametric model if it can be parametrized by a finite number of parameters, i.e. ~~there exists~~ There exists a finite dimensional parameter space $\Theta = \{(\theta_1, \theta_2, \dots, \theta_k)\}$ s.t. every element of \mathcal{F} is associated with an element of Θ .

ex: Everything we ~~see~~ saw in MATH 165 (more or less).

ex: Normal distributions in \mathbb{R} is a parametric model with two parameters:

$f(x)$ is a normal density if and only if there exist $\mu \in \mathbb{R}$ ("mean")
 $\sigma^2 \in \mathbb{R}_+$ ("variance")

s.t. $f(x) = \frac{1}{\sqrt{2\sigma^2}} \cdot \exp\left(\frac{-[x-\mu]^2}{2\sigma^2}\right)$.

- Parametric models make identifying a good estimate for the true density easier... just estimate the finitely many parameters! How hard can that be...
- If we consider \mathcal{F} to not have a finite parametrization, this is non-parametric statistics.

ex: Let $\mathcal{F} = \{f \in \mathcal{C}(\mathbb{R}) \mid f(x) \geq 0 \text{ and } \int_{\mathbb{R}} f(x) dx = 1\}$ be the space of all continuous densities. This is a big space of functions, and doesn't have a useful finite parametrization.

• Context: Given data $\{x_i\}_{i=1}^n$ ~~iid~~ ^{iid} X for X unknown,

- (1) Parametric: Find the best Gaussian to model X
- (2) Nonparametric: Find the best continuous density to model X

• Obviously (2) is less constrained.

- An underlying issue with statistics is how to decide if I have predicted well.
- That is, given data $X_1, \dots, X_n \overset{iid}{\sim} X$, how do I know if my predicted density or predicted ~~density~~ $f(X)$ is good or not? This is a problem that never really goes away, and can be studied on many levels.
- We will focus on the "classical" approach to understanding error in statistical estimation: bias-variance tradeoff.

✓ Density estimation is hard, and we will focus on an easier problem for now: point estimation, i.e. estimating a particular quantity of interest. We are especially interested in estimating the expected value of X , given only observations $X_1, \dots, X_n \overset{iid}{\sim} X$.

• More generally, let θ be an underlying quantity of interest, quite of a parameter in a parametric model (e.g. $\theta = E(X)$). θ itself is unknowable, so we would like to estimate it given (random) data $X_1, \dots, X_n \overset{iid}{\sim} X$.

• We can think of a method of estimation as a function on the data. This is a fundamental insight of statistics, because it allows for the machinery of analysis and probability to give us control.

• So, we will write ~~the~~ $\hat{\theta}(X_1, \dots, X_n)$ as a function that estimates θ , given

data $X_1, \dots, X_n \stackrel{iid}{\sim} X$.

ex: Let $X_1, \dots, X_n \sim X$, where $E(X)$ exists. A classical problem is to estimate $E(X)$. It is almost an article of faith that we should use $\frac{1}{n} \sum_{i=1}^n X_i$.

In 1-dimension, a quick simulation shows this to be effective for many X if n is large enough.

In fact the WLLN says this is a good idea!

Indeed, WLLN says, $\forall \epsilon > 0$,

$$\lim_{n \rightarrow \infty} P\left(\left|\frac{1}{n} \sum_{i=1}^n X_i - E(X)\right| > \epsilon\right) = 0.$$

$$\text{So, if } \left. \begin{array}{l} \theta = E(X) \\ \hat{\theta}(x_1, \dots, x_n) = \frac{1}{n} \sum_{i=1}^n x_i \\ \hat{\theta}_n \end{array} \right\} \xrightarrow{\text{WLLN}} \lim_{n \rightarrow \infty} P(|\hat{\theta}_n - \theta| > \epsilon) = 0. \quad \text{Pretty good!}$$

This motivates the idea of consistency.

Defn: A point estimator $\hat{\theta}(x_1, \dots, x_n) = \hat{\theta}_n$ is consistent if $\hat{\theta}_n \xrightarrow{P} \theta$.

A key insight is that $\hat{\theta}_n$ is a r.v. So, we can consider its expectation and variance.

Defn: Let $\hat{\theta}_n$ be an estimator of θ . ~~We say $\hat{\theta}_n$ is unbiased~~ The bias of $\hat{\theta}_n$ is $\text{bias}(\hat{\theta}_n) = E(\hat{\theta}_n) - \theta$, where the expectation is taken over $X_1, \dots, X_n \sim \mathcal{X}$. We say $\hat{\theta}_n$ is unbiased if $\text{bias}(\hat{\theta}_n) = 0$.

Let $\text{Var}(\hat{\theta}_n) = E([\hat{\theta}_n - E(\hat{\theta}_n)]^2)$ be the variance of $\hat{\theta}_n$ with respect to the sample $X_1, \dots, X_n \sim \mathcal{X}$. We are typically interested in understanding the "total" error of estimating:

$\text{MSE}(\hat{\theta}_n) = E([\hat{\theta}_n - \theta]^2)$, the mean square error.

Amazingly, this is interpretable into two components = model part v. random part.

Theorem (Bias-Variance Tradeoff): $\text{MSE}(\hat{\theta}_n) = \text{bias}(\hat{\theta}_n)^2 + \text{Var}(\hat{\theta}_n)$.

Proof: $E([\hat{\theta}_n - \theta]^2) \stackrel{A}{=} E([\hat{\theta}_n - E(\hat{\theta}_n)] + \underbrace{E(\hat{\theta}_n) - \theta}_B)^2$ $E([A+B]^2) = E A^2 + 2AB + E B^2$

$= E([\hat{\theta}_n - E(\hat{\theta}_n)]^2) + 2 E[\hat{\theta}_n - E(\hat{\theta}_n)] [E(\hat{\theta}_n) - \theta] + E([E(\hat{\theta}_n) - \theta]^2)$ $E([A+B]^2) = E A^2 + 2AB + E B^2$

$\underbrace{E([\hat{\theta}_n - E(\hat{\theta}_n)]^2)}_{\text{Var}(\hat{\theta}_n)} + 2 \underbrace{E[\hat{\theta}_n - E(\hat{\theta}_n)]}_{=0} \cdot \underbrace{[E(\hat{\theta}_n) - \theta]}_{\text{constant}} + E([E(\hat{\theta}_n) - \theta]^2) = \text{bias}(\hat{\theta}_n)^2$

$= \text{Var}(\hat{\theta}_n) + 2 (E(\hat{\theta}_n) - \theta) \cdot E[\hat{\theta}_n - E(\hat{\theta}_n)] + [E(\hat{\theta}_n) - \theta]^2$

$= \text{Var}(\hat{\theta}_n) + \text{bias}(\hat{\theta}_n)^2$ ■

$\text{bias}(\hat{\theta}_n) \approx 0$ if there is enough capacity in the model to fit well. $\text{Var}(\hat{\theta}_n) \approx 0$ if we have enough data to reliably estimate.